

# Reusability of FEM Software: A Program Family Approach

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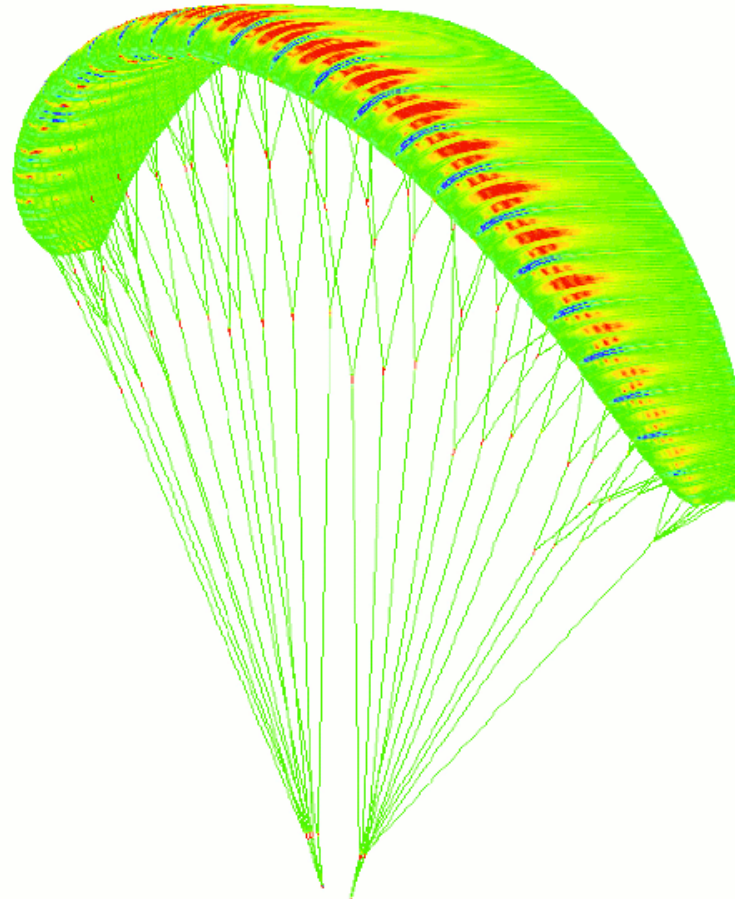
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# Outline

- Finite Element Method (FEM)
- Program Family
- A FEM Program Family: FEMBA
  - Goal-Oriented Commonality Analysis (CA)
  - Documentation
  - Code Generation

# Finite Element Method

- A numerical technique for solving PDEs
- A website maintained by Roger Young and Ian MacPhedran lists more than 100 public domain FEM programs



Maximum Principal Stress in a Paraglider  
Solved by **CalculiX**

# Program Family

- A set of programs that share a common set of features



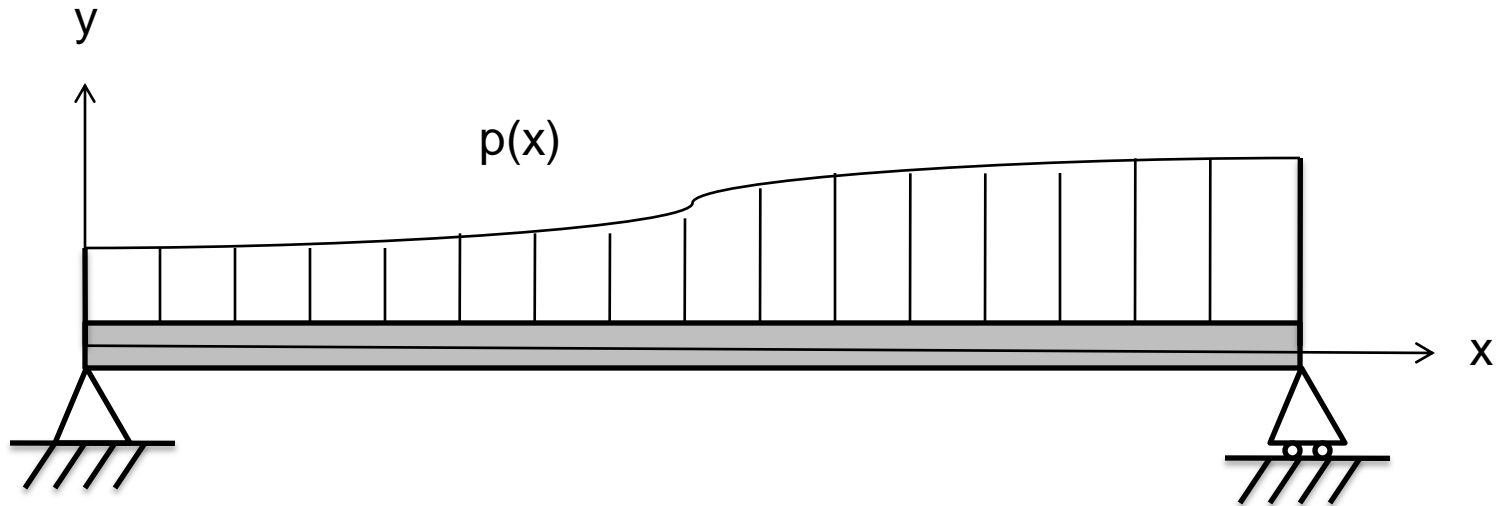
- A commonality: the protocol
- A variability: the number of features



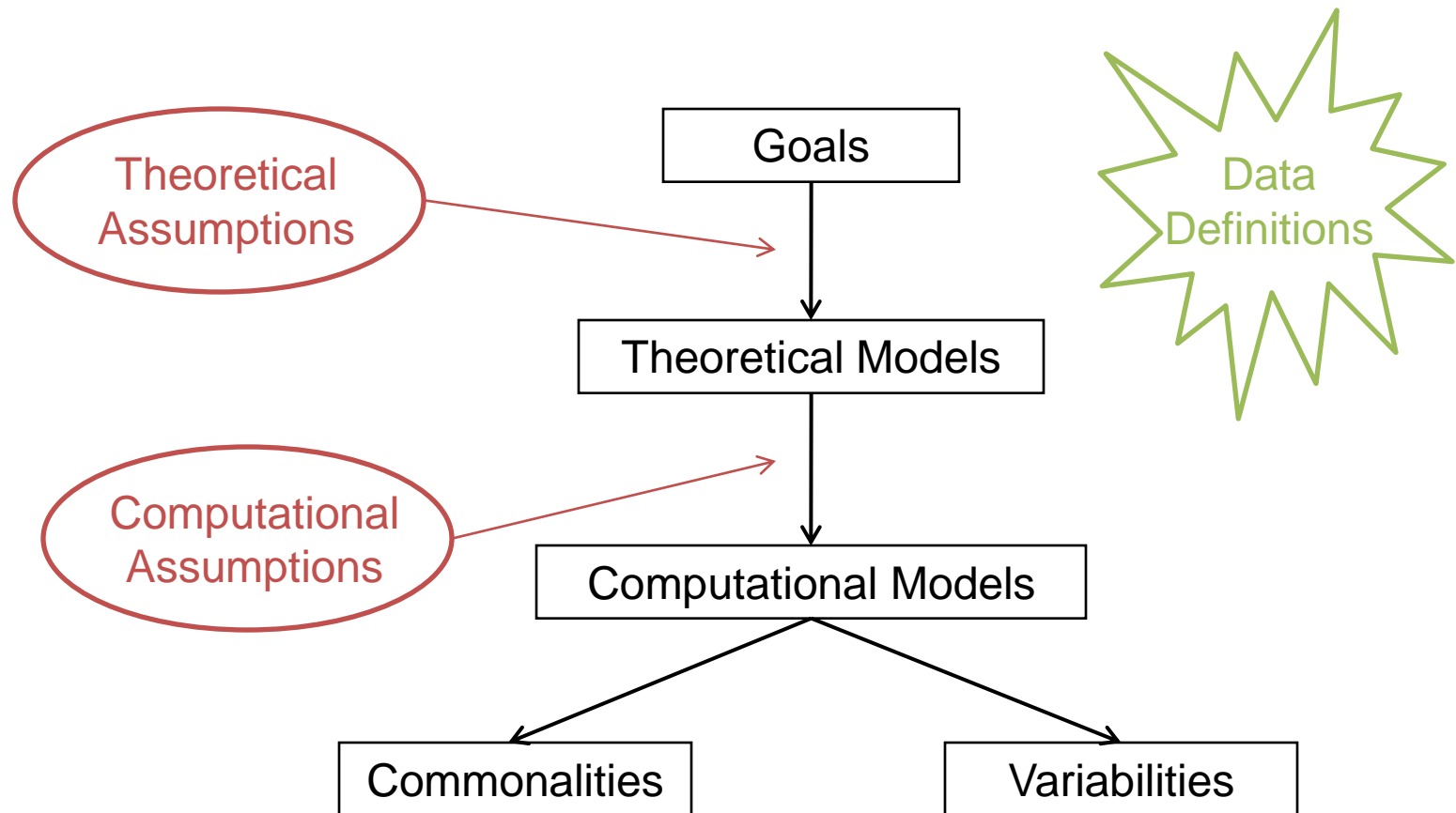
Pictures from CrunchGear

# A FEM Program Family: FEMBA

FEMBA simulates a beam under an applied load using FEM



# Goal-Oriented CA



# Examples of CA for FEMBA (1)

- **G1** (gDis): FEMBA can solve for the displacement of a beam;
- **TA7**: The weight of the beam is neglected;
- **TM1** (tmDis): The equation to be solved for displacement is  $d^4w/dx^4 = p(x)/EI$ ;
- **CA1** (caFEM): The problems are solved using FEM;
- **CM1** (cmDis): The formula for solving the displacement of each node is  $\mathbf{Ka} = \mathbf{F}$ ;

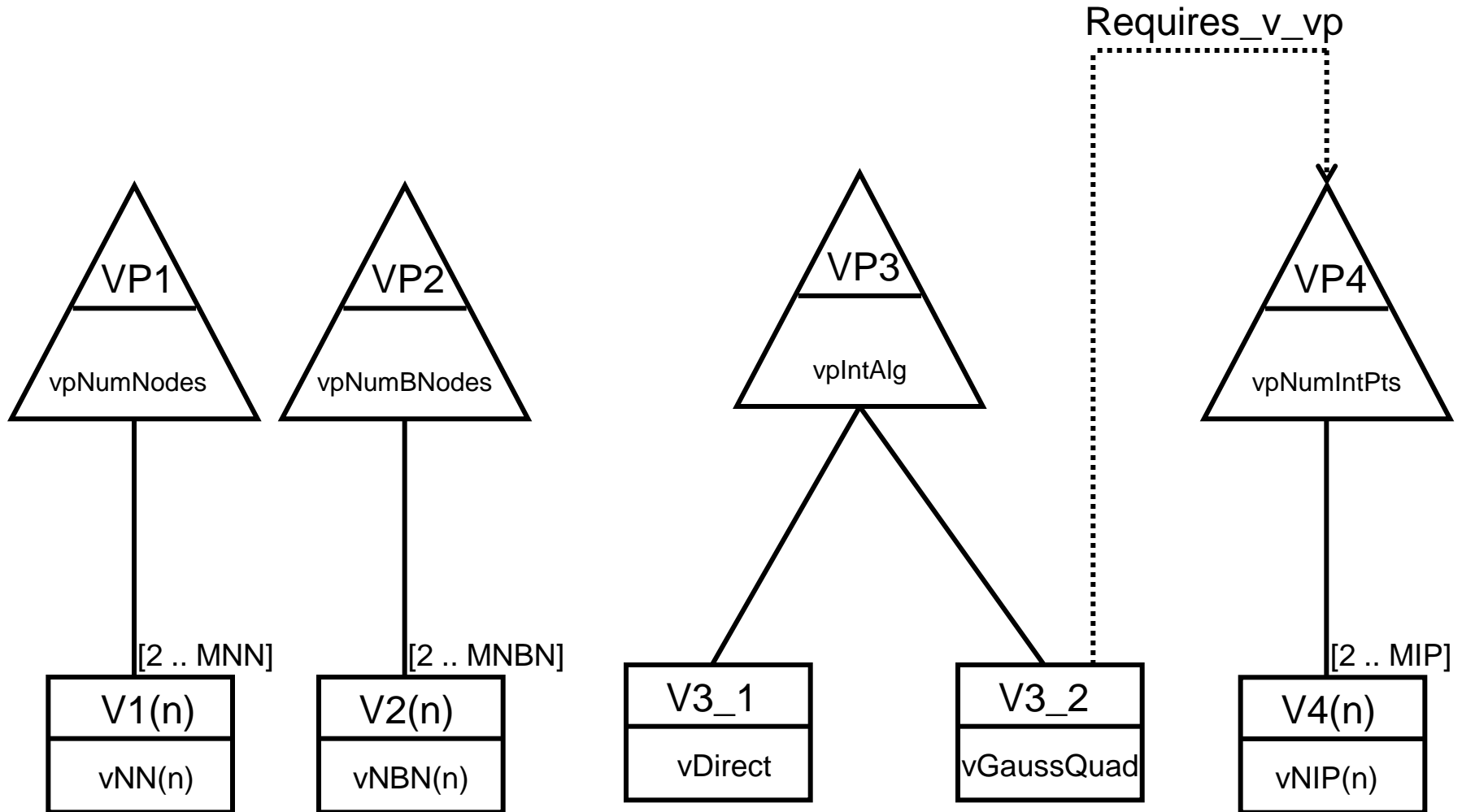
# Examples of CA for FEMBA (2)

- **C4** (cDOF): Each node has two degrees of freedom (DOF)
- **VP1**(vpNumNodes): Each element has different number of nodes
- **D5** (dStiff):  $\mathbf{K} = \int \mathbf{B}^T \mathbf{E} \mathbf{I} \mathbf{B} \, dx$

# Documentation

- A program usually needs to be changed to be reused
- Documentation of variabilities and traceability matrices can help with the changes

# Documentation: Variabilities



# Documentation: Traceability Matrix

Traceability Matrix between Requirements and Modules (partial)

	mInMesh	mOutput	mControl	mStiff	mLoad	...
...						
cShear		✓	✓			
vpNum Node	✓			✓	✓	
...						

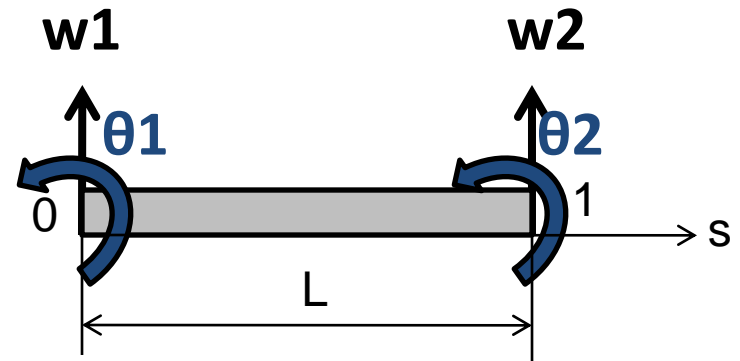
# Code Generation: Calculating K (1)

1. Find the shape functions

$$\phi_i(s) = c_{i1} + c_{i2}s + c_{i3}s^2 + c_{i4}s^3 \text{ for}$$

$$w = w_1\phi_1 + L\theta_1\phi_2 + w_2\phi_3 + L\theta_2\phi_4$$

$$\theta = w'$$



$$\phi_1(0)=1 \quad \phi_1'(0)=0 \quad \phi_1(1)=0 \quad \phi_1'(1)=0$$

$$\phi_2(0)=0 \quad \phi_2'(0)=1 \quad \phi_2(1)=0 \quad \phi_2'(1)=0$$

$$\phi_3(0)=0 \quad \phi_3'(0)=0 \quad \phi_3(1)=1 \quad \phi_3'(1)=0$$

$$\phi_4(0)=0 \quad \phi_4'(0)=0 \quad \phi_4(1)=0 \quad \phi_4'(1)=1$$

# Code Generation: Calculating K (2)

2. Compute kinematics matrix  $\mathbf{B}=\mathbf{A}\mathbf{N}$ , where  
A is the operator  $(d^2/ds^2)/L^2$  and  
 $\mathbf{N}=[\phi_1 \ L\phi_2 \ \phi_3 \ L\phi_4]$
3. Compute stiffness matrix  $\mathbf{K}=\int(\mathbf{B}^T\mathbf{E}\mathbf{I}\mathbf{B})dx$

# Code Generation for FEMBA

- Calculating  $K$  is time consuming
- Use Maple to generate code for variabilities
- Use information hiding to develop FEMBA

# Conclusion

- Program family approach can improve reusability by reusing commonalities
- Goal-oriented CA, documentation and code generation can improve reusability by helping with changes

Thank You !